

Advanced Mathematical Methods for Telemetry Analysis

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- **Outline**

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- **Does not contain US Export Controlled information**

Summary

- Spacecraft telemetry delivers an enormous amount of data.
 - *Usually and mostly about the hardware.*
- Advanced mathematical methods have the potential
 - *To detect weak early indications or precursors of anomalies,*
 - *To identify unexpected correlations in system measurements,*
 - *To identify major hardware degradation in advance.*
- These capabilities may lead to earlier and better behavior predictions
 - *For ground-based analysis of spacecraft operation.*
 - *Eventually, maybe better on-board anomaly prediction / detection,*
 - Even correction of some anomalies
- Experimentation is needed to understand what is and is not detectable.
 - *How far in advance anomalies can be detected.*
 - *Which advanced mathematical methods are more effective.*
 - *What other data would be useful.*

The big problem is software.

Spacecraft Telemetry Issues

- Classic analyses
 - *Acceptable intervals and short-term trends*
- Rarely
 - *Cross-mission norms and anomalies*
- Predictive models based on planned mission profile, and history of similar programs, satellites, or components
- In earlier papers,
 - *We advocated extensive software telemetry.*
 - *We also advocate more telemetry for detailed instrumentation.*
 - MUCH more!
 - We explain later how this choice need not be the bandwidth problem it might seem to be

Extend telemetry analyses to more software, cross-missions and longer times

Software Caused Failures

- NASA's Mars Climate Orbiter (23 September 1999):
 - *Different developers used different physical units in thruster commands.*
- NASA's Mars Polar Lander (03 December 1999):
 - *Software did not distinguish leg deployment from landing shocks.*
- ESA's Huygens Probe (14 January 2005):
 - *One communication channel (of two) was never commanded to turn on.*
- All three have something in common:
 - *They are attributable to insufficiently careful software or software design.*
 - In the ESA case, it was a CONOPS problem that more carefully designed software could have detected.
 - *Something quite simple went wrong quite disastrously.*
- The problem is that there are many millions of simple things that can go wrong.
 - *Similar issues occur in some military satellite failures.*
 - *Descriptions of these ones are more widely accessible.*

We have no development methods capable of managing this complexity.

Software Telemetry

- Each of these issues could have been found with more extensive software telemetry.
- Different context of reuse should have led to scrutiny of value ranges.
 - *“It has flown successfully before” is a wholly inadequate justification.*
 - *Values can be reported and compared to expected value ranges.*
- Simple on-board sanity checks should occur for all critical parameters.
 - *This is where the numbers hit the processors.*
 - *This is where they should be checked.*
- Ditto
 - *Every value put into a database should be checked.*
 - *Telemetry should announce all values received prior to execution.*
- Auditable chain of custody for every numerical parameter.
 - *Not all problems are software.*

These steps will help; they are far too seldom implemented, and by themselves, are not enough.

Advanced Mathematical Methods

- To provide perspective across:
 - *Long time periods*
 - *Measurements*
 - *Missions*
- Some example kinds of complex detailed analyses
 - *Robust Statistics*
 - *Grammatical Inference*
 - *Event Pattern Correlation*
 - *Time Series Analysis*
 - Hidden Markov Models
 - Dynamic Time Warping
 - *Fractal Dimension*
 - *Dimension Reduction*
 - *Manifold Discovery*
 - *Topological Data Analysis*

Many methods exist; we chose a few of them.

Some Example Applications

- Temporal characteristics detection
 - *“Regime change”*
 - Mission phases are planned well in advance
 - Expectable behavior can be predicted
 - *Statistics can be predicted,*
 - *Different for each phase*
 - *Signal texture definition and identification*
 - Expected noise level and pattern, general trend
 - Fractal dimension for change detection
 - *Each hardware measurement has relatively well-known known degradation and failure characteristics.*
 - Software is more difficult, because we know much less about degradation and failure of software components.

Some Example Applications (cont.)

- Correlations, expected and otherwise
 - *Time delayed correlations can detect potential causalities.*
 - *Distinguishing causality from correlation depends on deviation correlations.*
- Behavior in abstract trajectory spaces
 - *Long term behavior of measurements over time and correlations thereof*
 - *Dimension reduction to identify nominal behavior and first excursions.*
 - Computing expectable constraints

Some Practicalities

- Is this too much telemetry?
 - *We think the increased information outweighs the processing burden and decreases risk.*
 - *The increased information does not necessarily increase required bandwidth.*
- Compressed sensing for telemetry suites
 - *More telemetry, less bandwidth*
 - *Need to trust the compression process*
 - Process to detect measurement sequences outside the expected space
 - Also an occasional non-compressed item,
 - *used like tracers to verify compression process*

Some Practicalities (cont.)

- This is an example of dimension reduction
 - *Define the expected space of measurement sequences*
 - For each measurand separately (and some together)
 - *Use manifold discovery to determine what part of the space actually gets used*
 - This is also a prediction derived from nominal behavior
 - *And expectable anomalies*
 - Construct a low-dimensional manifold in the measurement sequence space
 - This is a common model with fewer parameters.
 - *Map from actual measurement sequences to the smaller manifold*
 - Fewer dimensions means fewer bits to send
 - Original measurement reconstructed from the values received
 - *and the known common model*

Conclusions and Prospects

- Exciting prospects for extracting more comprehensive information from telemetry
 - *Using a host of advanced mathematical methods (see the Appendix)*
- These computations need some serious experimentation for feasibility and location
 - *How much can be done on-board? on-line?*
 - *How much can only be done off-line or retrospectively?*
 - *How much isn't particularly helpful?*
 - *How much might be helpful with further development or research?*
- We need to collect much more extensive software telemetry for tracking the internal progress of computations.
 - *Happily, we can do that on the ground.*

Conclusions and Prospects (cont.)

- We need to experiment with software telemetry also
 - *What parts of the code are the most important to measure?*
 - decision points and other branches
 - function calls and parameters
 - interrupts and pre-emption
 - fixed point arithmetic computations
 - ...what else?
- We need new and much more extensive stress testing of units and components (to limit damage propagation or escalation).
 - *Can we prevent small errors from leading to catastrophic failure?*
 - *Can we prevent most errors from leading to catastrophic failure?*
 - *Study of error propagation through complex numerical calculations*
 - *Study of error propagation through non-numerical calculations*



Questions?

Appendix: Definitions and Examples of Selected Methods

- List of Selected Methods
 - *Robust Statistics*
 - *Grammatical Inference, Event Pattern Correlation*
 - *Time Series Analysis, Hidden Markov Models, Dynamic Time Warping*
 - *Fractal Dimension, Large Dimensions*
 - *Dimension Reduction, Random Projections*
 - *Manifold Discovery, Local Linear Embedding, ISOMAP*
 - *Topological Data Analysis*
- Define for each area
 - *What it is about*
 - Not formal definitions; those are available
 - *What it can do*
 - What it has already been used for, at least in a lab
 - *What it might be able to do*
 - With some extension and further development

This is a short informal introduction. Details can be found elsewhere.

Robust Statistics

- What it is
 - *Statistical computations that are not dependent on distribution assumptions*
 - *(every empirical distribution is usually assumed to be Gaussian; many are)*
- What it can do
 - *Identify outliers, identify vulnerabilities of any statistical summary*
 - *(what fraction of bad data can cause bad results)*
- What it might be able to do
 - *More reliable identification of noise (structured and not)*
 - *Better (less noisy) summaries of data*

Robust Statistics Example

- The example is about a sample set (where we consider different values for x)

$$\{0, 3, 7, 8, x\}.$$

- We can compute that the mean of this set is

$$m = 3.6 + 0.2 * x,$$

- and that the variance is

$$v = 11.44 - 1.44 * x + 0.16 * x^2.$$

- As x gets large, both of these increase without bound.
- The **breakdown point** of an estimator is the proportion (or number) of incorrect observations an estimator can handle before giving an (arbitrarily) incorrect result.

Robust Statistics Example (cont.)

- The robust "figure skating" rule is to omit the largest and smallest values.
- Then whenever x is larger than 8, the mean is 6 and the variance about 4.667
 - *The breakdown point of this method is 1 if the statistic is one-sided*
 - *(a second very large value will be retained),*
 - *and the method can sometimes work with 2 outliers*
 - *(when one is excessively large and one excessively small).*
- The **influence functions** for m and v are the algebraic expressions above, showing how m and v depend on x .

Grammatical Inference

- What it is
 - *Infer structure rules (syntax) from item sequences*
 - *Rules have the form LHS \implies RHS*
 - RHS is a sequence of terminal and non-terminal symbols
 - *terminal symbols correspond to items, so they do not change*
 - *non-terminal symbols correspond to classes of structured items*
 - LHS is also, with various restrictions that determine a classification
 - *PSG = Phrase Structure Grammar (at least one non-terminal)*
 - *CSG = Context Sensitive Grammar (one non-terminal in LHS changes to a sequence in RHS)*
 - *CFG = Context-Free Grammar (only one non-terminal)*
 - *RG = Regular Grammar (further restrictions on grammar)*

Grammatical Inference (cont.)

- What it can do
 - *Find compact rules for complex hierarchical behavior structures*
 - Structure recognition (parsing)
 - *Make sure the language contains enough correct sets*
 - Generation of random sets
 - *Make sure the language contains few incorrect sets*
- What it might be able to do
 - *New mathematics to define partially ordered set grammars*
 - *(see Event Patterns below)*
 - Inference of pattern grammars from complex data

Grammatical Inference Example

- Start with a large finite set of strings (sequences of characters)
- Problem is inherently ambiguous
 - *Many grammars generate languages that contain exactly the same strings*
 - *Usually want the smallest one*
- Sample inference rules (each makes a new non-terminal symbol and substitutes it into the strings)
 - *If $A . B$ occurs a lot, infer new rule $Z \implies A . B$*
 - (and replace $A . B$ with Z wherever it occurs)
 - *If $X . A . Y$ and $X . B . Y$ occur a lot, infer new rule $Z \implies A | B$*
 - (and replace A and B with Z wherever they occur)
 - (we can retain the context $X _ Y$ in the rule if it is a CSG)
 - *If sequences of A 's occur a lot, infer new rules $Z \implies A$ and $Z \implies Z . A$*
 - (and replace sequences of A 's with Z wherever they occur)
 - (or just $Z \implies A^+$ if RG)
- Problem: cannot infer CFG with only positive examples
- ~~Inferring recursion is difficult, but useful (it distinguishes CFG from RG)~~

Event Pattern Correlation

- What it is
 - *Matching complex occurrence patterns separated in space and time*
 - *General partially ordered sets, instead of merely sequences*
- What it can do
 - *Make connections from similar structure*
- What it might be able to do
 - *Highly scalable algorithms for correlations among many sequences*
 - Want something with complexity less than quadratic if possible
 - *New mathematics of non-sequence correlation*
 - Extension of previous algorithms for grammatical inference and parsing
 - *Much more flexible event pattern detection and correlation*
 - Then add a temporal component

Event Pattern Correlation Example

- Identifying TCP connection attempts
 - *Client side: Start in Initial state*
 - Send SYN
 - *SYN_SENT: Wait for SYN and ACK (or close from client)*
 - Receive SYN and ACK
 - Send ACK
 - Connection Established
 - *Server side: Go to LISTEN mode (Wait for SYN)*
 - Receive SYN
 - Send SYN and ACK
 - *SYN_RCVD: Wait for ACK*
 - Receive ACK
 - Connection Established
 - Receive RST, go to Initial
- These message sends can be detected
- Many coordination protocols can be identified this same way

Time Series Analysis

- This topic is too big, consider Hidden Markov Models (HMM), Dynamic Time Warping (DTW)
- What HMM is
 - *Data implies maximum likelihood model parameters*
 - Model implies sample data
 - *EM algorithm is the iteration of this process*
- What it can do
 - *Determine certain kinds of hidden structure (HMMs are an example)*
 - *Impute missing data*
 - *Compute sensitivity of models to imputed data*
- What it might be able to do
 - *Algorithms to speed up EM iteration*
 - *Other hidden structures besides periodicity (via Fourier analysis)*
 - Cascaded structures (e.g., periodicity depends on mode, mode changes according to Finite State Machine or Markov Model)

Hidden Markov Model Example

- Long sequence of English text (words only)
- Assume two-state Markov chain and size 27 (letters + space) output alphabet
- Compute Maximum Likelihood estimate for transition probabilities and output maps
- Apply forward-backward algorithm (linear in the total length of the string)
 - *Compute transition matrix and output mapping that maximize the likelihood of the observed string*
 - *Then the states clearly correspond to vowels and consonants*
 - Letters y, w, and r are slightly more ambiguous than others
- Similar results hold for up to 12 states
 - *Phonetically meaningful categories derived from ordinary English spelling*

Dynamic Time Warping

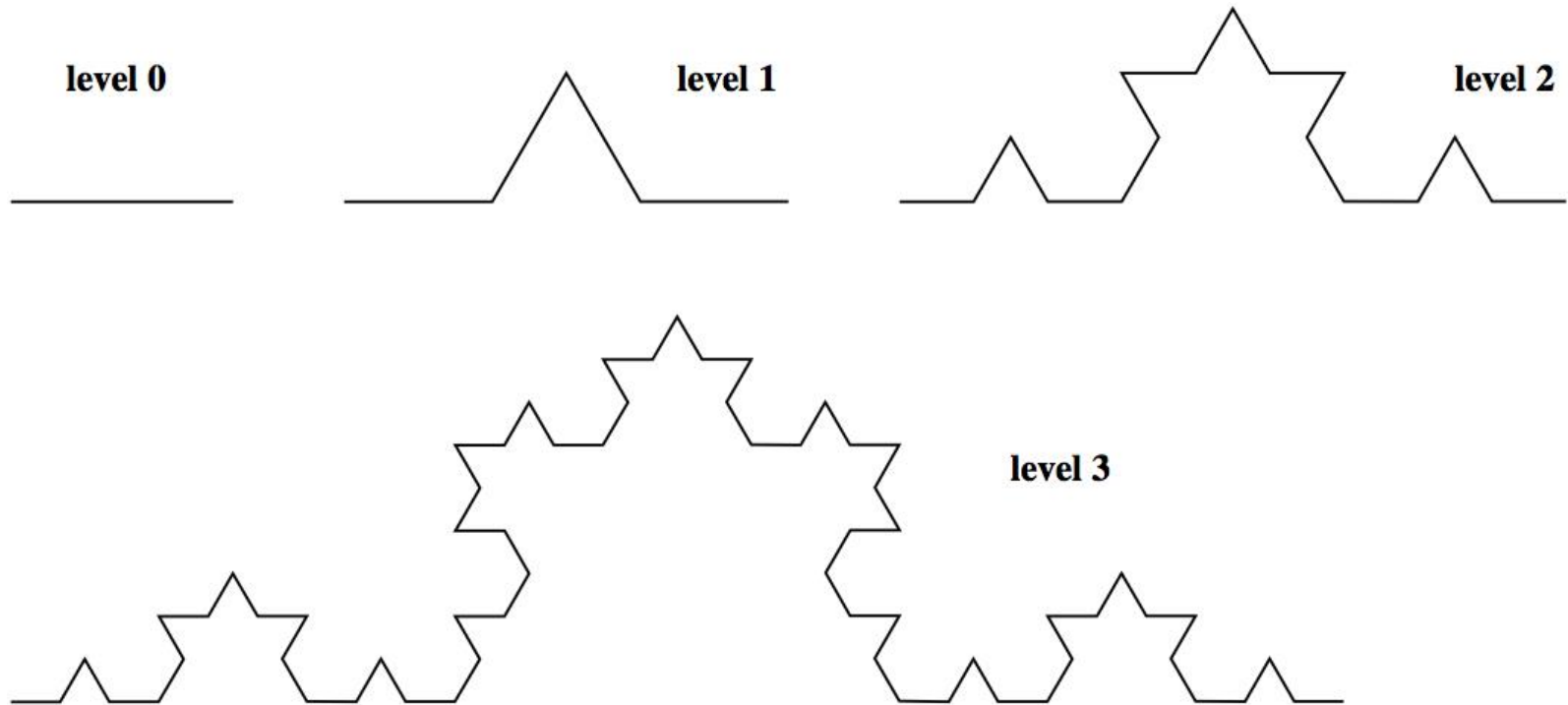
- What DTW is
 - *Matching one time series to another, with different and possibly variable time progressions*
- What it can do
 - *Match speech patterns to templates*
 - *Match business rhythms of different duration*
- What it might be able to do
 - *Extend to a plane to match images in a new registration style*
 - Local distortion
 - *Match computers running the same code by output signals or by heat generation / power use*

Fractal Dimension

- What it is
 - *Determine fractal dimension of a set, which determines minimum guaranteed embedding dimension (using tuple map)*
- What it can do
 - *Bound the computation of complex dynamics*
 - If $d =$ fractal dimension,
 - then any $m > 2 * d + 1$ is sufficient for embedding the dynamics
 - (and smaller dimensions can work)
- What it might be able to do
 - *More reliable computation of fractal dimension*
 - *Much faster computation of a close upper bound*
 - *Hard to spoof*

Fractal Dimension Example

- Koch curve, dimension $\log 4 / \log 3 \sim 1.26186$
- The dimension of any *self-similar* figure can be computed fairly readily.



Things are Tricky in Many Dimensions

- The n-volume V_n of the unit n-sphere decreases rapidly to zero as n increases
 - $V_0 = 1$, $V_1 = 2$, $V_2 = \pi$, $V_3 = (4/3) * \pi$ (initial values, known values)
 - $V_{\{n\}} / V_{\{n-2\}} = 2 * \pi / n$ for $n \geq 2$,
 - *which ratio monotonically decreases for all $n \geq 1$,*
 - *and the n-volume V_n decreases for $n \geq 7$ (after increasing for $n < 7$)*
- If we inscribe an n-sphere in an n-cube, the n-volume ratio goes rapidly to zero
 - *Eventually, other unit n-spheres can be packed into the corners disjointly*
 - *(Martin Gardner devoted an entire column to these issues)*
- The volume of an n-annulus (n-sphere shell), with inner radius = 90% outer radius is almost the same as the volume of the n-sphere, and the ratio goes to 1 as n increases
 - $\text{ratio} = 1 - (0.9)^n$

Almost everything happens at the boundaries or in the corners.

Dimension Reduction

- What it is
 - *Structure preserving map from high-dimensional space into low-dimensions*
 - Different structures need different algorithms to compute different maps
 - *Nearby pair distances*
 - *Local linear relations*
 - *Geodetic distances*
 - *Tangent space alignments*
 - Generally choose how many dimensions in advance
 - *and see later how well it worked*
 - Could conceivably use an intrinsic dimensionality like Fractal Dimension

Dimension Reduction (cont.)

- What it can do
 - *Reduces computational effort, sometimes a lot (millions or more dimensions to hundreds or even just dozens)*
 - *Images, video and other signals, abstract trajectories and other event patterns are all high-dimensional data*
 - *Relationship and other connection patterns are high-dimensional data*
 - *Trajectories of other values can be considered as elements in a high-dimensional abstract trajectory space*
- What it might be able to do
 - *All of these can be simplified with some structure preserved*
 - Usefully? We don't know yet
 - *More different kinds of preserved structures*
 - *Data-dependent algorithm choice*
 - *Faster and more robust algorithms (better source data uncertainty management)*

Dimension Reduction Example

- Non-linear map (J.Sammon)
- Given a point set X in Real^D for large D , we want a mapping
 - $f : X \rightarrow \text{Real}^d$
 - usually with $d=2$ or $d=3$ and minimum **distortion**
- Compare $d(f(x),f(y))$ to $d(x,y)$ over all pairs x, y in X
 - *Distortion is sum of squared distance differences*
 - $(d(f(x),f(y)) - d(x,y))^2$
 - *Normalized by original distance $d(x,y)$ to emphasize preserving small distances*
 - *Each point in X is mapped separately, so there are $d * |X|$ variables*
- Simple (if time-consuming) optimization problem
 - *Many global minima (every permutation of X , every isometry of Real^d), so we need some criterion to limit translations*
 - Maybe one point is origin, always mapped to 0
 - Maybe sum of images is 0
 - Maybe choose $d+1$ points to anchor to a particular isometry in Real^d

Some Theorems

- Johnson-Lindenstrauss Theorem
 - *Any n point set in any Euclidean space can be embedded in k dimensions*
 - $k = O(\log n / \epsilon^2)$
 - *without distorting any pair distance by more than a factor of*
 - $1 \pm \epsilon$
 - *for any ϵ with $0 < \epsilon < 1$.*

 - *The issue is to find the smallest useful value of the constant for k .*

 - *The weird part is that Random Linear Projections almost always work.*
 - There is lots of research on how well restricted classes of projections work.

Some Theorems (cont.)

- Concentration of Measure Theorem

- Write S^{n-1} for the $(n-1)$ -sphere in n -space, $\{x \text{ in } \text{Real}^n \mid |x| = 1\}$.

- If $f : S^{n-1} \rightarrow \text{Real}$ is 1-Lipschitz

- (i.e., $|f(x) - f(y)| \leq |x - y|$ for all x, y),

- and if $s(\cdot)$ is a normalized measure on the sphere

- (i.e., $s(A)$ is the ratio of the area of A to the area of the sphere),

- Then

1. There is at least one real number M (called a median for f) for which

- $s(\{x \mid f(x) \leq M\}) = 1/2 = s(\{x \mid f(x) \geq M\})$,

2. $s(\{x \mid |f(x) - M| > \varepsilon\}) \leq 2 * \exp(-n * \varepsilon^2 / 2)$

- (i.e., f is very seldom far from M , so it is almost constant)

Manifold Discovery

- What it is
 - *Identify low-dimensional manifold in high-dimensional data (example of dimension reduction)*
- What it can do
 - *Discover unexpected and previously unknown constraints*
 - Local linear structure
 - Other neighborhood properties
 - Connected distance properties
- What it might be able to do
 - *Better management of data content and noise reduction*
 - Compressed sensing
 - *Dynamic characteristics of high-dimensional images and signals*
 - Track changes, notice trends, identify fluctuations
 - *Allows interpolation for new data points*
 - *Hard to spoof*

LLE, ISOMAP

- Two methods for Dimension Reduction
- LLE = Local Linear Embedding
 - *Local structure is defined by the best linear approximation of a point by its near neighbors, recorded in a coefficient matrix*
 - *Then the projection is the set of points that best preserves the coefficient matrix*
- ISOMAP
 - *Local structure is defined as the graph of its near neighbors;*
 - Distance is measured in edge lengths
- There are many others; all depend on a choice of neighborhood
 - *Distance or count threshold for size of neighborhood*
 - *Few or no studies of the effects of such choices*
- Concentration of measure theorem makes all distance-based methods suspect
 - *Examples can be found in the literature*

Topological Data Analysis

- What it is
 - *Fast homology computations for complex high-dimensional structures*
 - *(mapping complex geometric and topological structures to computable algebraic structures)*
- What it can do
 - *Summarize complex connectivity structures at all scales, robust to noisy data*
- What it might be able to do
 - *Compute sensitivity of structure to noise level*
 - *More effective image pyramid (less compression in slowly varying parts of the image)*
 - *Detect fundamental change in organizational relationships and other structures*
 - *Detect subtle differences among correct, erroneous, and fake data*
 - *The ``tidy set'' is a significant computational reduction (size and therefore time).*

Second List

- The lead candidates for a next round of study are:
 - *Uncertainty propagation*
 - *Identification of missing data and its potential utility to guide collection requests*
 - *Object extraction from images and signals*
 - *Flow mapping and non-explicit differential equations*
 - *Natural Language Processing (in multiple languages)*
 - *Graph theoretic analyses*
 - *Spatial-Temporal Reasoning*
 - *Advanced steganography*

There are, of course, many potentially useful methods we have not listed here.

Further Information

- For questions and / or comments, please contact the author

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